



Evaluation of Side-Channel Attacks Using α -Information

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Outline

Motivation

α -Information Theory

Evaluation of Side-Channel Attacks



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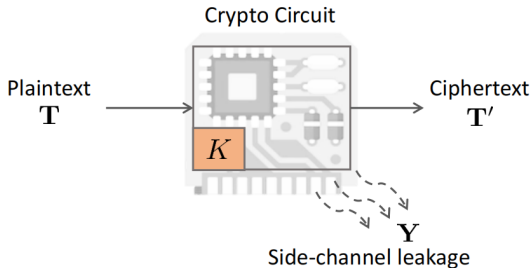
Motivation

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Motivation

- Side-Channel Attacks:



- **Information-theoretic tools** have been frequently used in the side-channel analysis.

Motivation

Chérisey et al. (CHES'19) establish some universal inequalities between **the probability of success** of a side-channel attack and **the minimum number of queries** to reach a given success rate.

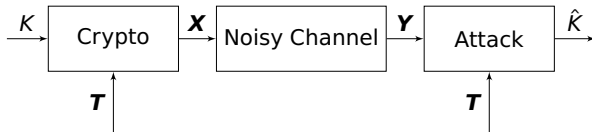
This result is:

- valid for **any** leakage model, **any** kind of attack.
- with the best possible knowledge on the attacker's side.

They mainly use two information measures:

- **Mutual Information:** $I(K; Y) = \mathbb{E}_Y \sum_k p(k|y) \log \frac{p(k|y)}{p(k)}$
(k : the secret, y : the leakage.)
- **Bianry Divergence:** $d(p||q) = p \log \frac{p}{q} + (1 - p) \log \frac{1-p}{1-q}$
(where p, q are two probability distributions.)

Side-Channel Model



- K : a secret key; normally we assume $K \sim \mathcal{U}(M)$;
- $\mathbf{T} = (T_1, T_2, \dots, T_q)$: a q -element vector, each element T_i is a plain or cypher text;
- $\mathbf{X} = (X_1, X_2, \dots, X_q)$: the output of the side-channel; the leakage function $\mathbf{X} = f(K, \mathbf{T})$ is deterministic;
- $\mathbf{Y} = (Y_1, Y_2, \dots, Y_q)$: traces measured by the attacker;
- \hat{K} : the guess of the secret key;
- \mathbb{P}_S : the probability of success, defined as $\mathbb{P}_S = \mathbb{P}(K = \hat{K})$; it's different from **success rate**.

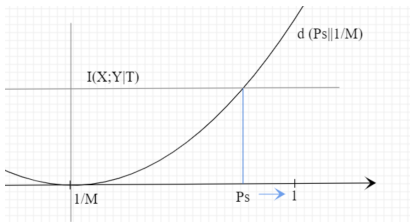
Evaluation of Side-Channel Attack

Main Theorem

One has the following upper bound on the probability of success \mathbb{P}_s :

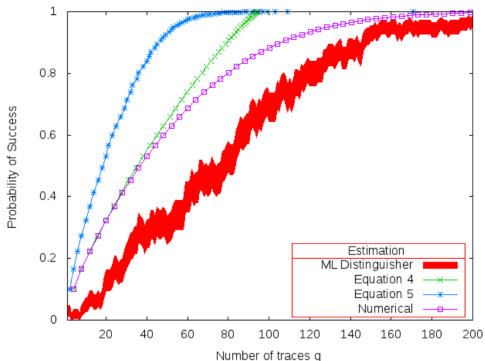
$$I(\mathbf{X}, \mathbf{Y}|\mathbf{T}) \geq d(\mathbb{P}_s \| \frac{1}{M})$$

- As shown in the following figure, $d(\mathbb{P}_s \| \frac{1}{M})$ is increasing in \mathbb{P}_s . Hence this inequality gives an upper bound on \mathbb{P}_s when $\mathbb{P}_s \geq 1/M$.



- One can evaluate \mathbb{P}_s by calculating the numerical value of $I(\mathbf{X}, \mathbf{Y}|\mathbf{T})$.

Bounds on Probability of Success



In this figure(Chérisey et al., CHES'19):

- the purple line: the numerical value of $I(X, Y|T)$;
- the blue and green lines: some explicit formula bounds.
- ML distinguisher is optimal if leakage model is known.

Properties

To prove the main theorem, the following properties of mutual information turn out to be essential:

- **Conditional Consistency (CC):** If T is independent of (X, Y) then

$$I(X; Y|T) = I(X; Y)$$

- **Uniform Expansion Property (UEP):** If $K \sim \mathcal{U}(M)$ and it is independent of T , then

$$I(K; Y|T) = H(K) - H(K|YT) = \log M - H(K|YT)$$

- **Data Processing Inequality (DPI):** If $W - X - Y - Z$ forms a conditional Markov chain given T , then

$$I(X; Y|T) \geq I(W; Z|T)$$

- **Fano's Inequality:** $H(K|\hat{K}) \leq H_2(\mathbb{P}_e) + \mathbb{P}_e \log_2(M - 1)$

$$\iff I(K; \hat{K}) \geq d(\mathbb{P}_s \| \frac{1}{M})$$

Objective

Our aims:

- make it more flexible by introducing a Rényi parameter α ;
- extend the work of Chérisey et al. to α -information quantities depending on a parameter α ;
- obtain tighter bounds by changing the value of α .

⇒ need an appropriate definition of $I_\alpha(X; Y|T)$ with four properties :

CC + UEP + DPI + Fano's inequality



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α -Information Theory

Let p, q be two probability distributions. We use the following notations:

$$\|p\|_{\alpha} = \left(\sum p^{\alpha}\right)^{1/\alpha}$$
$$\langle p\|q\rangle_{\alpha} = \left(\sum p^{\alpha}q^{1-\alpha}\right)^{1/\alpha}$$

- **α -entropy** (Rényi, 1961):

$$H_{\alpha}(P) = \frac{\alpha}{1-\alpha} \log \|p\|_{\alpha}$$

- **α -divergence** (Rényi, 1961):

$$D_{\alpha}(P\|Q) = \frac{1}{\alpha-1} \log \langle p\|q\rangle_{\alpha}^{\alpha}$$

α -Information Theory

Their conditional versions:

- **Conditional α -entropy** (Arimoto, 1975):

$$H_\alpha(X|Y) = \frac{\alpha}{1-\alpha} \log \mathbb{E}_Y \|p_{X|Y}\|_\alpha$$

- **Conditional α -divergence** (Verdú, 2015):

$$D_\alpha(P_{Y|X} \| Q_{Y|X} | P_X) = \frac{1}{\alpha-1} \log \mathbb{E}_X \langle p_{Y|X} \| q_{Y|X} \rangle_\alpha$$

Among several definitions of α -information, Sibson's proposal seems to be the most appropriate one (Verdú, 2015).

- **α -information** (Sibson, 1969):

$$I_\alpha(X; Y) = \frac{\alpha}{\alpha-1} \log \mathbb{E}_Y \langle p_{X|Y} \| p_X \rangle_\alpha$$

- **Conditional α -information** (Liu et al., ITW'21): our proposal of conditional α -information is

$$I_\alpha(X; Y|Z) = \frac{\alpha}{\alpha-1} \log \mathbb{E}_Z \mathbb{E}_{Y|Z} \langle p_{X|YZ} \| p_{X|Z} \rangle_\alpha$$

Conditional α -Information

Among many proposed definitions in the literature, our definition is the only one that satisfies the following properties:

- **Conditional Consistency (CC):** If T is independent of (X, Y) then

$$I_\alpha(X; Y|T) = I_\alpha(X; Y)$$

- **Uniform Expansion Property (UEP):** If $K \sim \mathcal{U}(M)$ is uniformly distributed independent of T , then

$$I_\alpha(K; Y|T) = H_\alpha(K) - H_\alpha(K|YT) = \log M - H_\alpha(K|YT)$$

- **Data Processing Inequality (DPI):** If $W - X - Y - Z$ forms a conditional Markov chain given T , then

$$I_\alpha(X; Y|T) \geq I_\alpha(W; Z|T)$$

- **Rioul's Generalized Fano Inequality (GFI)** (Rioul, GSI'21):

$$I_\alpha(X; Y) \geq d_\alpha(\mathbb{P}_s(X|Y) \parallel \mathbb{P}_s(X))$$



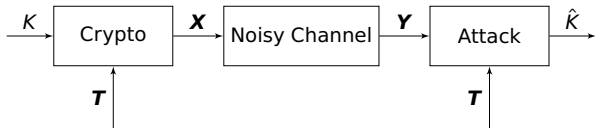
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Evaluation of Side-Channel Attack



Theorem (Upper Bound on \mathbb{P}_S)

One has the following upper bound on the probability of success \mathbb{P}_S :

$$I_\alpha(\mathbf{X}, \mathbf{Y} | \mathbf{T}) \geq d_\alpha(\mathbb{P}_S \| \frac{1}{M})$$

Evaluation of Side-Channel Attack

Proof.

Because $K - \mathbf{X} - \mathbf{Y}$ is a Markov chain given \mathbf{T} ,

$$I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) \geq I_\alpha(K, \mathbf{Y}|\mathbf{T}) \quad (\text{DPI})$$

Because \mathbf{X} is a deterministic function of K and $\mathbf{T}, \mathbf{X} - K - \mathbf{Y}$ is a Markov chains given \mathbf{T} , which gives us

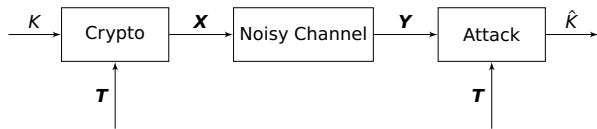
$$I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) \leq I_\alpha(K, \mathbf{Y}|\mathbf{T}) \quad (\text{DPI})$$

So $I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) = I_\alpha(K, \mathbf{Y}|\mathbf{T})$. Then one has

$$\begin{aligned} I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) &= I_\alpha(K, \mathbf{Y}|\mathbf{T}) \geq I_\alpha(K; \hat{K}|\mathbf{T}) && (\text{DPI}) \\ &= \log M - H_\alpha(K|\hat{K}, \mathbf{T}) && (\text{UEP}) \\ &\geq \log M - H_\alpha(K|\hat{K}) && (*) \\ &= I_\alpha(K, \hat{K}) && (\text{UEP}) \\ &\geq d_\alpha(\mathbb{P}_s(K|\mathbf{Y})\|\mathbb{P}_s(K)) && (\text{GFI}) \end{aligned}$$

*: condition reduce α -entropy. □

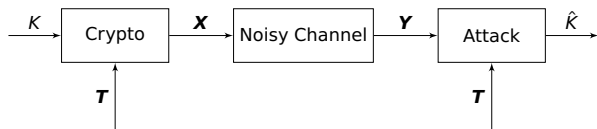
Evaluation of Side-Channel Attack



Theorem (Upper Bound on \mathbb{P}_S)

$$I_\alpha(\mathbf{X}, \mathbf{Y} | \mathbf{T}) \geq d_\alpha(\mathbb{P}_S \| \frac{1}{M})$$

Evaluation of Side-Channel Attack



Theorem (Upper Bound on \mathbb{P}_S)

$$I_\alpha(\mathbf{X}, \mathbf{Y} | \mathbf{T}) \geq d_\alpha(\mathbb{P}_S \| \frac{1}{M})$$

We consider an **implementation of the AES**, with the **Hamming weight leakage model** and **additive white Gaussian noise (AWGN) channel**.

$$\mathbf{Y} = \mathbf{X} + \mathbf{N} = w_H(S(\mathbf{T} \oplus K)) + \mathbf{N} \quad (i = 1, 2, \dots, q) \quad (1)$$

- w_H : the Hamming weight
- S : an S-box permutation
- $\mathbf{N} = (N_1, \dots, N_q)$, N_i are i.i.d $\sim \mathcal{N}(0, \sigma^2)$

Numerical Simulations

$$\mathbf{Y} = w_H(S(\mathbf{T} \oplus K)) + \mathbf{N} \quad (i = 1, 2, \dots, q)$$

Aim: compute

$$I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) = I_\alpha(K, \mathbf{Y}|\mathbf{T}) = \frac{\alpha}{\alpha - 1} \log \mathbb{E}_{\mathbf{T}} \mathbb{E}_{\mathbf{Y}|\mathbf{T}} \left(\sum_k p_{K|\mathbf{T}}^\alpha p_{K|\mathbf{T}}^{1-\alpha} \right)^{\frac{1}{\alpha}} \quad (2)$$

We compute $I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T})$ using **Monte Carlo simulation**.

Monte Carlo methods rely on **repeated random sampling** to obtain numerical results.

By the law of large numbers, **integrals described by the expected value of some random variable** can be approximated by taking the empirical mean (a.k.a. the sample mean) of independent samples of the variable.

Numerical Simulations

$I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T})$ can be written as

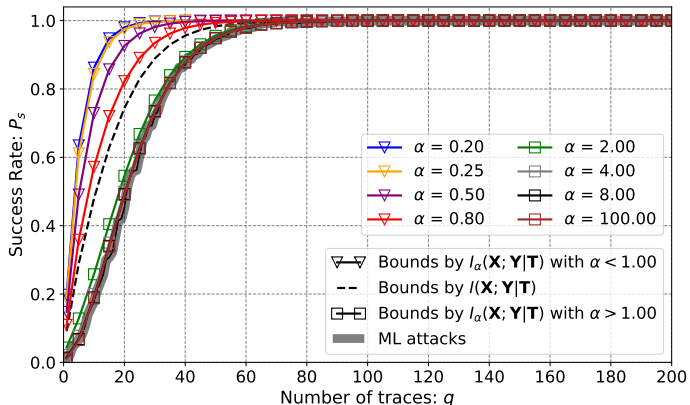
$$I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) = \frac{\alpha}{\alpha - 1} \log \left(\mathbb{E}_{\mathbf{Y}|\mathbf{T}} \frac{(\sum_k p(k|\mathbf{t}) p^\alpha(\mathbf{y}|\mathbf{t}, k))^\frac{1}{\alpha}}{p(\mathbf{y}|\mathbf{t})} \right). \quad (3)$$

Therefore, it can be estimated by using Monte-Carlo simulation in the following way:

$$\begin{aligned} \exp \left(\frac{\alpha - 1}{\alpha} I_\alpha(\mathbf{X}, \mathbf{Y}|\mathbf{T}) \right) &\approx \lim_{N_C \rightarrow \infty} \frac{1}{N_C} \sum_{j=1}^{N_C} \frac{(\sum_k p(k|\mathbf{t}^j) p^\alpha(\mathbf{y}^j|\mathbf{t}^j, k))^\frac{1}{\alpha}}{p(\mathbf{y}^j|\mathbf{t}^j)} \\ &= \lim_{N_C \rightarrow \infty} \frac{1}{N_C} \sum_{j=1}^{N_C} \frac{(\sum_k p(k) p^\alpha(\mathbf{y}^j|\mathbf{t}^j, k))^\frac{1}{\alpha}}{\sum_k p(k) p(\mathbf{y}^j|\mathbf{t}^j, k)}, \end{aligned}$$

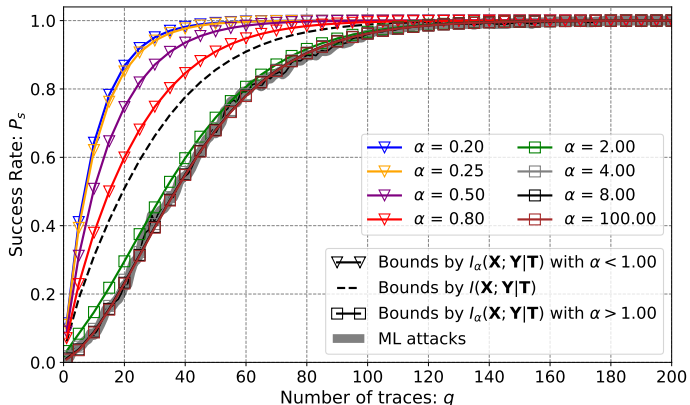
where $\mathbf{t}^j \sim \mathcal{U}(\mathbb{F}_{2^8}^q)$ and $\mathbf{y}^j \sim \mathcal{N}(f(\mathbf{t}^j, k^j), \sigma^2 \mathbf{I}_q) \in \mathbb{R}^q$ by choosing $k^j \sim \mathcal{U}(\mathbb{F}_{2^8})$ and $f(\mathbf{t}^j, k^j) = w_H(S(\mathbf{t}^j \oplus k^j))$.

Numerical Result



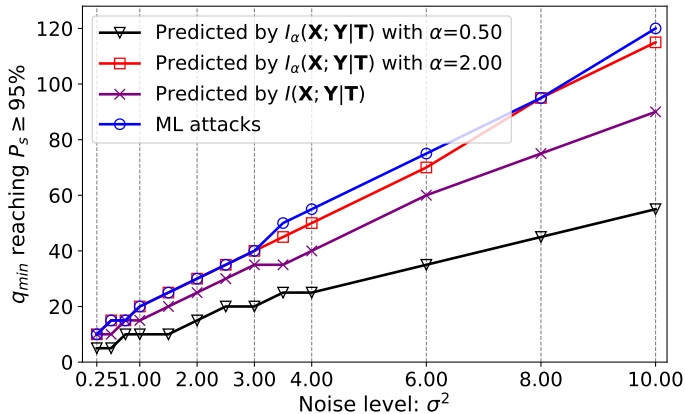
Noise level: $\sigma = 4$.

Numerical Result

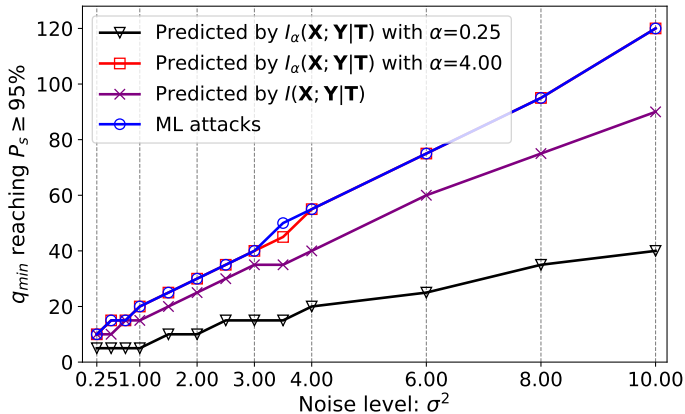


Noise level: $\sigma = 8$

Numerical Result



Numerical Result





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Thanks for your attention!

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