Fuzzy Logic

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Imprecision and fuzziness

- usual way of speaking (ex: a young person)
- objects (no clear boundaries, coarse segmentation...)
- relations (ex: left of, quite close)
- observations (ex: it is raining moderately)
- type of knowledge available (ex: the caudate nucleus is close to the lateral ventricle)
- question to be answered (ex: go towards this object while remaining at some security distance)

Definitions: fuzzy sets (L. Zadeh, 1965)

- Space S (image space, space of characteristics, etc.)
- Fuzzy set: $\mu: \mathcal{S} \to [0,1] \mu(x) =$ membership degree of x to μ
- Support: $Supp(\mu) = \{x \in S, \mu(x) > 0\}$

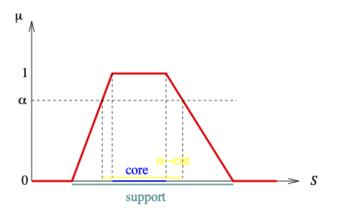
• Core / kernel:
$$\{x \in \mathcal{S}, \mu(x) = 1\}$$

•
$$\alpha$$
-cut: $\mu_{\alpha} = \{x \in \mathcal{S}, \mu(x) \ge \alpha\}$

• Cardinality: $|\mu| = \sum_{x \in S} \mu(x)$ (for S finite)

• Convexity: $\forall (x, y) \in S^2, \forall \lambda \in [0, 1], \mu(\lambda x + (1 - \lambda)y) \ge \min(\mu(x), \mu(y))$

■ Fuzzy number: convex fuzzy set on ℝ, u.s.c., unimodal, with compact support. Example: LR-fuzzy sets.



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First basic operations (L. Zadeh, 1965)

• Equality:
$$\mu = \nu \Leftrightarrow \forall x \in \mathcal{S}, \mu(x) = \nu(x)$$

- Inclusion: $\mu \subseteq \nu \Leftrightarrow \forall x \in \mathcal{S}, \mu(x) \leq \nu(x)$
- Intersection: $\forall x \in \mathcal{S}, (\mu \cap \nu)(x) = \min(\mu(x), \nu(x))$
- Union: $\forall x \in S, (\mu \cup \nu)(x) = \max(\mu(x), \nu(x))$
- Complementation: $\forall x \in S, \mu^{C}(x) = 1 \mu(x)$

Properties:

- consistency with binary set operations
- $\mu = \nu \Leftrightarrow \mu \subseteq \nu$ and $\nu \subseteq \mu$
- fuzzy complementation is involutive: $(\mu^{C})^{C} = \mu$
- intersection and union are commutative and associative
- intersection and union are idempotent and mutually distributive
- intersection and union are dual with respect to the complementation: $(\mu \cap \nu)^{C} = \mu^{C} \cup \nu^{C}$

•
$$(\mu \cup \nu)_{\alpha} = \mu_{\alpha} \cup \nu_{\alpha}$$
, etc.

 $\mathsf{BUT}: \mu \cap \mu^{\mathsf{C}} \neq \emptyset, \ \mu \cup \mu^{\mathsf{C}} \neq \mathcal{S}$

Definitions: possibility theory (L. Zadeh, D. Dubois, H. Prade

Possibility measure: function Π from $2^{\mathcal{S}}$ into [0, 1] such that:

- $\Pi(\emptyset) = 0$
- $\square \ \Pi(\mathcal{S}) = 1$
- $\exists \forall I \subseteq N, \forall A_i \subseteq S(i \in I), \ \Pi(\cup_{i \in I} A_i) = \sup_{i \in I} \Pi(A_i)$

Necessity measure: $\forall A \subseteq S$, $N(A) = 1 - \Pi(A^C)$

1 $N(\emptyset) = 0$

2
$$N(S) = 1$$

$$\exists \forall I \subseteq N, \forall A_i \subseteq S(i \in I), \ N(\cap_{i \in I} A_i) = \inf_{i \in I} N(A_i)$$

Useful properties:

•
$$\max(\Pi(A), \Pi(A^{C})) = 1$$
, $\min(N(A), N(A^{C})) = 0$

$$\blacksquare \ \Pi(A) \geq N(A)$$

 $N(A) > 0 \Rightarrow \Pi(A) = 1, \quad \Pi(A) < 1 \Rightarrow N(A) = 0$

•
$$N(A) + N(A^{C}) \le 1$$
, $\Pi(A) + \Pi(A^{C}) \ge 1$

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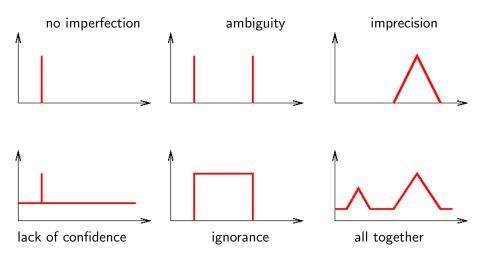
Possibility distribution: function π from S into [0,1] with the normalization condition $\sup_{x \in S} \pi(x) = 1$

- Interpretation of π as the membership function defining the fuzzy set of possible values.
- In the finite case: $\Pi(A) = \sup\{\pi(x), x \in A\}$ (for $A \subseteq S$) Conversely: $\forall x \in S$, $\pi(x) = \Pi(\{x\})$

■
$$N(A) = 1 - \sup\{\pi(x), x \notin A\} = \inf\{1 - \pi(x), x \in A^{C}\}$$

- Degree of similarity (notion of distance).
- Degree of plausibility (that an object from which only an imprecise description is known is actually the one one wants to identify).
- Degree of preference (fuzzy class = set of "good" choices), close to the notion of utility function.

Representing different types of imperfection



Fuzzy complementation / negation function c from [0, 1] into [0, 1] such that:

$$1 c(0) = 1$$

$$c(1) = 0$$

- 3 c is involutive, i.e. $\forall x \in [0,1], c(c(x)) = x$
- 4 c is strictly decreasing

General form of continuous complementations: $c(x) = \varphi^{-1}(1 - \varphi(x))$ with $\varphi : [0,1] \to [0,1], \varphi(0) = 0, \varphi(1) = 1, \varphi$ strictly increasing.

Example:
$$\varphi(x) = x^n \Rightarrow c(x) = (1 - x^n)^{1/n}$$

Triangular norms: fuzzy intersection / conjunction t-norm $t : [0, 1] \times [0, 1] \rightarrow [0, 1]$ such that:

- 1 commutativity, i.e. $\forall (x,y) \in [0,1]^2$, t(x,y) = t(y,x);
- **2** associativity, i.e. $\forall (x, y, z) \in [0, 1]^3$, t(t(x, y), z) = t(x, t(y, z));
- **3** 1 is unit element, i.e. $\forall x \in [0,1], t(x,1) = t(1,x) = x;$
- **4** increasingness with respect to the two variables:

 $\forall (x,x',y,y') \in [0,1]^4, \ (x \leq x' \text{ and } y \leq y') \Rightarrow t(x,y) \leq t(x',y').$

Moreover: t(0,1) = t(0,0) = t(1,0) = 0, t(1,1) = 1, and 0 is null element ($\forall x \in [0,1], t(x,0) = 0$).

Examples of t-norms: min(x, y), xy, max(0, x + y - 1).

Triangular conorms: fuzzy union / disjunction t-conorm $T : [0,1] \times [0,1] \rightarrow [0,1]$ such that:

- 1 commutativity, i.e. $\forall (x,y) \in [0,1]^2$, T(x,y) = T(y,x);
- 2 associativity, i.e. $\forall (x, y, z) \in [0, 1]^3$, T(T(x, y), z) = T(x, T(y, z));
- **3** 0 is unit element, i.e. $\forall x \in [0,1], T(x,0) = T(0,x) = x;$

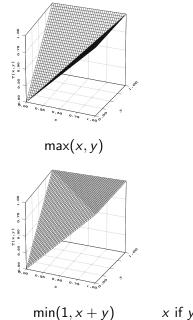
4 increasingness with respect to the two variables

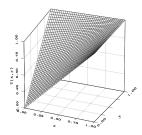
Moreover: T(0,1) = T(1,1) = T(1,0) = 1, T(0,0) = 0, and 1 is null element ($\forall x \in [0,1], T(x,1) = 1$).

Examples of t-conorms: $\max(x, y)$, x + y - xy, $\min(1, x + y)$.

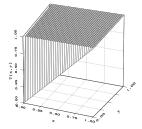
Duality: pair (t, T) such that $\forall (x, y) \in [0, 1]^2$, T(c(x), c(y)) = c(t(x, y))

Other combination operators (mean, symmetrical sums, etc.) \Rightarrow information fusion





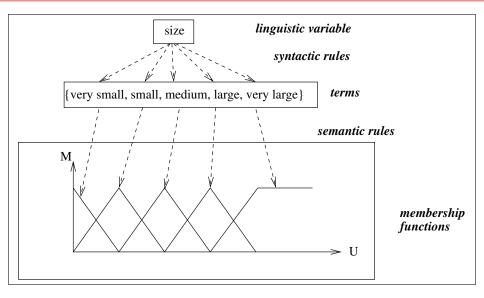




x if y = 0, y if x = 0, 1 otherwise

Symbolic A

Linguistic variable (L. Zadeh)



Imprecise reasoning

- Difference between data and knowledge
- Classical logic:
 - language
 - semantics (interpretations, truth values)
 - syntax (axioms and inference rules)
- Human reasoning: flexible, allows for imprecise statements
- Gradual predicates:
 - continuous referential
 - typicality

Examples: *this person is young, this person is rather young...* – Propositions that can be neither completely true nor completely false.

= unable to say whether a proposition is true or not

- because information is incomplete, vague, imprecise ⇒ possibility
- because information is contradicting or fluctuating ⇒ probability

certainty degree \neq truth degree

"It is probable that he "He is very far is far from his goal" from his goal"

- Fuzzy logic: propositions with truth degrees
- Possibilistic logic: propositions with (un)certainty degrees

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Fuzzy logic

$$\mu_{A \wedge B}(x, y) = t(\mu_A(x), \mu_B(y))$$

Disjunction: X is A or Y is B

$$\mu_{A \lor B}(x, y) = T(\mu_A(x), \mu_B(y))$$

Negation

$$\mu_{\neg A}(x) = c(\mu_A(x))$$

■ Variables in a product space: X with values in U, Y with values $V \Rightarrow$ conjunction = Cartesian product: X is A and Y is B

$$\mu_{A\times B}(x,y) = t(\mu_A(x),\mu_B(y))$$

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Fuzzy implications

- Classical propositional logic: $(A \rightarrow B) \equiv (B \lor \neg A)$
- Fuzzy logic: implication from a negation and a t-conorm
 - A and B crisp:

$$I(A,B)=T(c(A),B)$$

• A and B fuzzy:

$$I(A,B) = \inf_{x} T(c(\mu_A(x)), \mu_B(x))$$

• Examples
$$(c(a) = 1 - a)$$
:

$T(a,b) = \max(a,b)$	$I(a,b) = \max(1-a,b)$	Kleene-Diene
$T(a,b) = \min(1,a+b)$	$I(a,b) = \min(1,1-a+b)$	Lukasiewicz
T(a,b) = a + b - ab	I(a,b) = 1 - a + ab	Reichenbach

Fuzzy logic: residual implications from a t-norm

$$I(A,B) = \sup\{X \mid t(X,A) \le B\}$$

Adjunction: $t(X, A) \leq B \Leftrightarrow X \leq I(A, B)$

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Fuzzy reasoning

Classical propositional logic

- Modus ponens: $(A \land (A \rightarrow B)) \vdash B$
- Modus tollens: $((A \rightarrow B) \land \neg B) \vdash \neg A$
- Syllogism: $((A \rightarrow B) \land (B \rightarrow C)) \vdash (A \rightarrow C)$
- Cuntraposition: $(A \rightarrow B) \vdash (\neg B \rightarrow \neg A)$

…

Fuzzy (generalized) modus ponens

Rule :

if
$$X$$
 is A then Y is B

Knowledge or observation:

X is A'

Conclusion:

$$Y \text{ is } B'$$

 $\mu_{B'}(y) = \sup_{x} t(\mu_{A'}(x), I(\mu_A(x), \mu_B(y)))$



IF (x is A AND y is B) THEN z is C IF (x is A OR y is B) THEN z is C

. . .

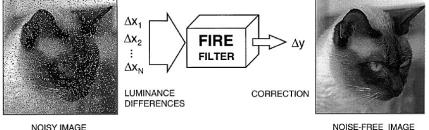
 α : truth degree of x is A β : truth degree of y is B γ : truth degree of z is C

Satisfaction degree of the rule:

$$I(t(\alpha,\beta),\gamma) = T(c(t(\alpha,\beta)),\gamma))$$
$$I(T(\alpha,\beta),\gamma) = T(c(T(\alpha,\beta)),\gamma))$$

Example in image filtering

IF a pixel is **darker** than its neighbors THEN **increase** its grey level ELSE IF a pixel is **brighter** than its neighbors THEN decrease its grey level ELSE unchanged



NOISE-FREE IMAGE

F. Russo et al.

Possibilistic logic

• Possibility measure on a Boolean algebra of logical formulas: $\Pi : R \to [0, 1]$ such that:

 $\Pi: B \rightarrow [0,1]$ such that:

$$\Pi(\bot) = 0 \Pi(\top) = 1$$

•
$$\forall \varphi, \phi, \Pi(\varphi \lor \psi) = \max(\Pi(\varphi), \Pi(\psi))$$

- ∀φ, Π(∃xφ) = sup{Π(φ[a|x]), a ∈ D(x)} (with D(x) = domain of variable x, and φ[a|x] obtained by replacing occurrences of x in φ by a)
- Normalized possibility distribution: $\pi : \Omega \rightarrow [0, 1]$ such that $\exists \omega \in \Omega, \ \pi(\omega) = 1 \ (\Omega = \text{set of interpretations})$

$$\Pi(\varphi) = \sup\{\pi(\omega), \ \omega \models \varphi\}$$

Necessity measure:

$$N(arphi) = 1 - \Pi(\neg arphi)$$

 $\forall \varphi, \phi, \ N(\varphi \land \psi) = \min(N(\varphi), N(\psi))$ Example: default rule "if A then B"

$$\sqcap(A \land B) \geq \sqcap(A \land \neg B)$$

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Possibilistic modus ponens

Rule:

$$N(A \rightarrow B) = \alpha$$

Knowledge or observation:

$$N(A) = \beta$$

Conclusion:

 $\min(\alpha,\beta) \leq N(B) \leq \alpha$

Stratified knowledge bases

$$\mathsf{KB} = \{(\varphi_i, \alpha_i), i = 1...n\}$$

- $\alpha_i \in (0, 1]$: certainty degree or priority of the (propositional) formula φ_i
- means $N(\varphi_i) \geq \alpha_i$
- knowledge: one is certain at level α_i that φ_i is true
- preference: goal φ_i with priority α_i

Representation as a possibility distribution on the set of interpretations Ω (induced by the underlying propositional logic):

• for one formula (φ, α) :

$$\forall \omega \in \Omega, \ \pi_{(\varphi, \alpha)}(\omega) = \left\{ egin{array}{cc} 1 & \textit{if} \ \omega \models \varphi \ 1 - lpha & \textit{otherwise} \end{array}
ight.$$

for the knowledge base:

$$\forall \omega \in \Omega, \ \pi_{\mathsf{KB}}(\omega) = \min_{i=1\dots n} \{1 - \alpha_i, \omega \models \neg \varphi_i\} = \min_{i=1\dots n} \max(1 - \alpha_i, \varphi_i(\omega)\}$$
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Example of inference rule:

$$((\neg p \lor q, \alpha); (p \lor r, \beta)) \vdash (q \lor r, \min(\alpha, \beta))$$

Inconsistency degree of KB : $1 - \max_{\omega \in \Omega} \pi_{KB}(\omega)$

- Complete base: $\forall \varphi$, either $KB \vdash \varphi$, or $KB \vdash \neg \varphi$
- Ignorance on φ : *KB* $\nvdash \varphi$ and *KB* $\lor \neg \varphi$ ⇒ simplest possibilistic model:

$$\Pi(\varphi) = \Pi(\neg \varphi) = 1$$

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